

# EMC 2015

## Tooling and Infrastructure

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# Introducing PICO



- ▶ Telepresence Robot from Aldebaran
  - ▶ Robot type: [Jazz](#)
- ▶ Sensors:
  - ▶ Laser Range Finder (LRF)
  - ▶ Wheel encoders (odometry)
  - ▶ Asus Xtion Depth sensor
  - ▶ 170° wide-angle camera
  - ▶ Sonar

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  - ▶ Holonomic base (omni-wheels)
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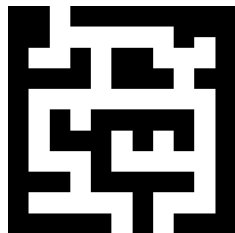
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- ▶ Computer:
  - ▶ [Intel I7](#)
  - ▶ Running [Ubuntu 14.04](#)

# The Assignment

- ▶ Let PICO navigate through a maze and find and go to the exit.
- ▶ You have to:
  - ▶ try to be *as fast as possible*
  - ▶ deal with *dynamics* in the environment (a moving door)
- ▶ You can use:
  - ▶ The *Laser Range Finder* to detect walls and doors
  - ▶ The *encoder* data from the wheels
- ▶ Competition day: *June 17*



# Intermediate Assignment

- ▶ **Corridor Competition:** Let PICO drive through a corridor and go through the side exit.
- ▶ You have to:
  - ▶ try to be **as fast as possible**
- ▶ You can use:
  - ▶ The **Laser Range Finder** to detect walls
  - ▶ The **encoder** data from the wheels
- ▶ Competition day: **May 13**



# Ubuntu

- ▶ Linux-based operating system
- ▶ Use version **14.04** (not 14.10!)
- ▶ 32- and 64-bit (**64-bit recommended**)
- ▶ Easy dual boot installation with e.g., Windows
- ▶ Download: [www.ubuntu.com](http://www.ubuntu.com)
  - ▶ Any problems? → [Check the wiki](#).
  - ▶ No info? → Ask the ICT Servicedesk or contact us.





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- ▶ However, you are still **allowed** to use ROS!

# C++

- ▶ We will use C++ as programming language
- ▶ C++ is object-oriented C
  - ▶ “C with Classes”
  - ▶ Encapsulate data and functionality within objects
- ▶ Is a **powerful** but **complex** programming language.
- ▶ However, we provide a **software framework** to get you started

# Creating code: Qt Creator

- ▶ Integrated Development Environment
  - ▶ Advanced code editor
- ▶ Many advantages over 'simple editors':
  - ▶ Syntax highlighting
  - ▶ Code completion
  - ▶ Visual compiler feedback
  - ▶ Static code checking
  - ▶ Refactoring tools
  - ▶ Parenthesis matching
  - ▶ ...



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- ▶ Use to **store** and maintain your code on the server
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- ▶ More info later

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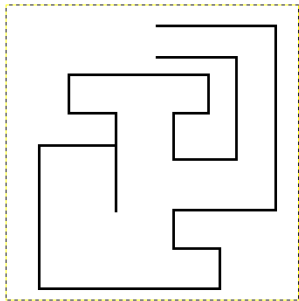
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- ▶ **Integrates** well with our provided software
  - ▶ If you your software runs on the simulator, it runs on the robot
  - ▶ This does **not** guarantee that it will also work...

You still need to test on the real system!

# PICO Simulator





# Wiki

- ▶ EMC Wiki:
  - ▶ [http://cstwiki.wtb.tue.nl/index.php?title=Embedded\\_Motion\\_Control](http://cstwiki.wtb.tue.nl/index.php?title=Embedded_Motion_Control)
  - ▶ Info on practical assignment, installation, getting started
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- ▶ Overall use:
  - ▶ Everyone can [edit](#)
  - ▶ If you see a mistake: [correct it](#)
  - ▶ If you had a problem and know how to fix it: [add it](#)

# Recap

- ▶ Assignment: solve maze with PICO robot

# Recap

- ▶ Assignment: [solve maze](#) with [PICO](#) robot
- ▶ OS: [Ubuntu 14.04](#)
- ▶ Programming language: [C++](#)
- ▶ Code editor: [Qt Creator](#)
- ▶ Version control: [git](#)
- ▶ Simulation: [PICO simulator](#)
- ▶ Documentation: [Wiki](#)

# Getting Started

- ▶ Check the wiki:
  - ▶ [http://cstwiki.wtb.tue.nl/index.php?title=Embedded\\_Motion\\_Control](http://cstwiki.wtb.tue.nl/index.php?title=Embedded_Motion_Control)
- ▶ Follow the [tutorials](#) on the wiki:
  - ▶ Ubuntu, C++, Qt Creator
  - ▶ Coming soon: simulator, software framework, git

Tutor name will be sent to you  
It is *your* responsibility to get in touch with your tutor