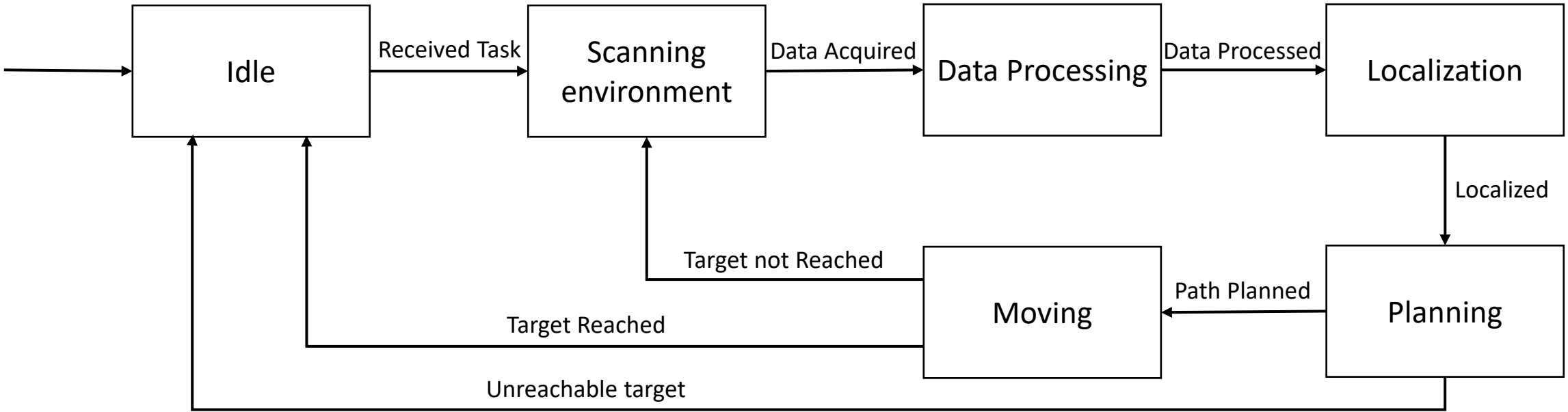
Idle
Received Task
Scanning environment
Data Acquired
Data Processing
Data Processed
Localization
Localized
Planning
Path Planned
Moving
Target not Reached
Target Reached
Unreachable target