## **OLAUKO: Robots Everywhere**

0LAUK0: Robots Everywhere				2/4/2021																				
Group 05		Project Start: Today:			<					-														
		Display Week:			10 May, 20					7 May, 20					May, 202						lay, 2021			
TASK	ASSIGNED TO	PROGRESS	START	END	10 11 м т	12 13 w т	14 F	15 S	16 17 s м	18 T	19 2 w	0 21 F F	22 2 s s	3 24 м	25 т	26 27 w т	28 F	29 S	30 s	31 M	1 2 т v	2 3 w т	4 F	5 S
Planning	All	4000/	40/4/24	22/4/24								_		_				$\vdash$					$\vdash$	
Planning: Develop Milestones Planning: Project Plan	Quentin	100% 95%	22/2/21	22/4/21 29/4/21	+							_												
Planning: Fix and addapt plan	Quentin	10%	4/2/21	18/6/21																				
Research	quentin	10/0	-1/2/21	10/0/21															-		-			
Research: State of the art (papers as project referal)	All		19/4/21	29/4/21								_												-+
Research: Space and Orbital knowledge	Tim		19/4/21	6/5/21																				
Research: Previously planned missions to Titan	lve		22/4/21	6/5/21																				
Research: Conditions for 'life'	Peter		22/4/21	6/5/21																				
Research: Scanner types and how they can be used	Quentin		22/4/21	6/5/21																				
Research: Potential Software/material needed to realise deliverable	Johan		22/4/21	6/5/21																				
Research: How can data samples be collected	Peter		22/4/21	6/5/21																				
Research: Programming method for deliverable	Quentin		29/4/21	6/5/21																				
Research: Communication methods (for technical deliverable)	lve		6/5/21	13/5/21																				
Deliverables:												_												
Deliverables: Type of deliverable (T = Technical ; (P) = Program)	All		22/4/21	29/4/21										_									$ \longrightarrow $	
Deliverables: Datasets	Tim		13/5/21	20/5/21																			$ \longrightarrow $	
Deliverables: Communication system	lve		13/5/21	27/5/21																				
Deliverables (T): Working camera mount	Peter		13/5/21																					
Deliverables (T): Potential virtual testing environment	Peter		13/5/21	27/5/21														$\vdash$	$\rightarrow$	$\rightarrow$			$\vdash$	
Deliverables (T): Multi-varied terrain mobility	Johan Tim		13/5/21	27/5/21														$\vdash$					$\vdash$	
Deliverables (T): Potential testing methods Deliverables (P): Software decision (what will be used to create program)	All		13/5/21 13/5/21	27/5/21 27/5/21	+																			
Deliverables (P): Mapping system	Quentin		13/5/21	27/5/21																		_		
Deliverables (P): create a suitible 'memory'	Johan		13/5/21	27/5/21																				
Deliverables (P): Development in goal based decision making	lve		13/5/21	27/5/21	++																		$\vdash$	-+
Deliverables (P): Development in self learning system	Quentin		13/5/21																					
Wiki Page:																								
WIki Page: Topics to be covered in wiki	All		29/4/21	6/5/21																				
Wiki Page: Project description	Tim		22/4/21	29/4/21																				
Wlki Page: Project Plan	Quentin		22/4/21	29/4/21																				
Wiki Page: Logbook	All		19/4/21	18/6/21																				
Wiki Page: Project Method	Peter		29/4/21	6/5/21																				
Wlki Page: Research	All		29/4/21	13/5/21																				
Wlki Page: Deliverable development	Johan		6/5/21	18/6/21																				
WIki Page: Literature ans Sources	All		22/4/21	18/6/21															<u> </u>	<u> </u>			<u> </u>	
Final Deadlines:					$\downarrow$													$ \square $				_	$\vdash$	$ \rightarrow $
Final Deadlines: Presentation	All	0%	10/6/21	18/6/21																				
Final Deadlines: Completed Deliverable	All	0%	10/5/21	18/6/21																				
Final Deadlines: Demonstration of functioning deliverable	All	0%	10/5/21	18/6/21																				
Final Deadlines: Completed Gantt Diagram	All	10%	22/4/21	18/6/21																				