

Design Group 6

R. Beenders

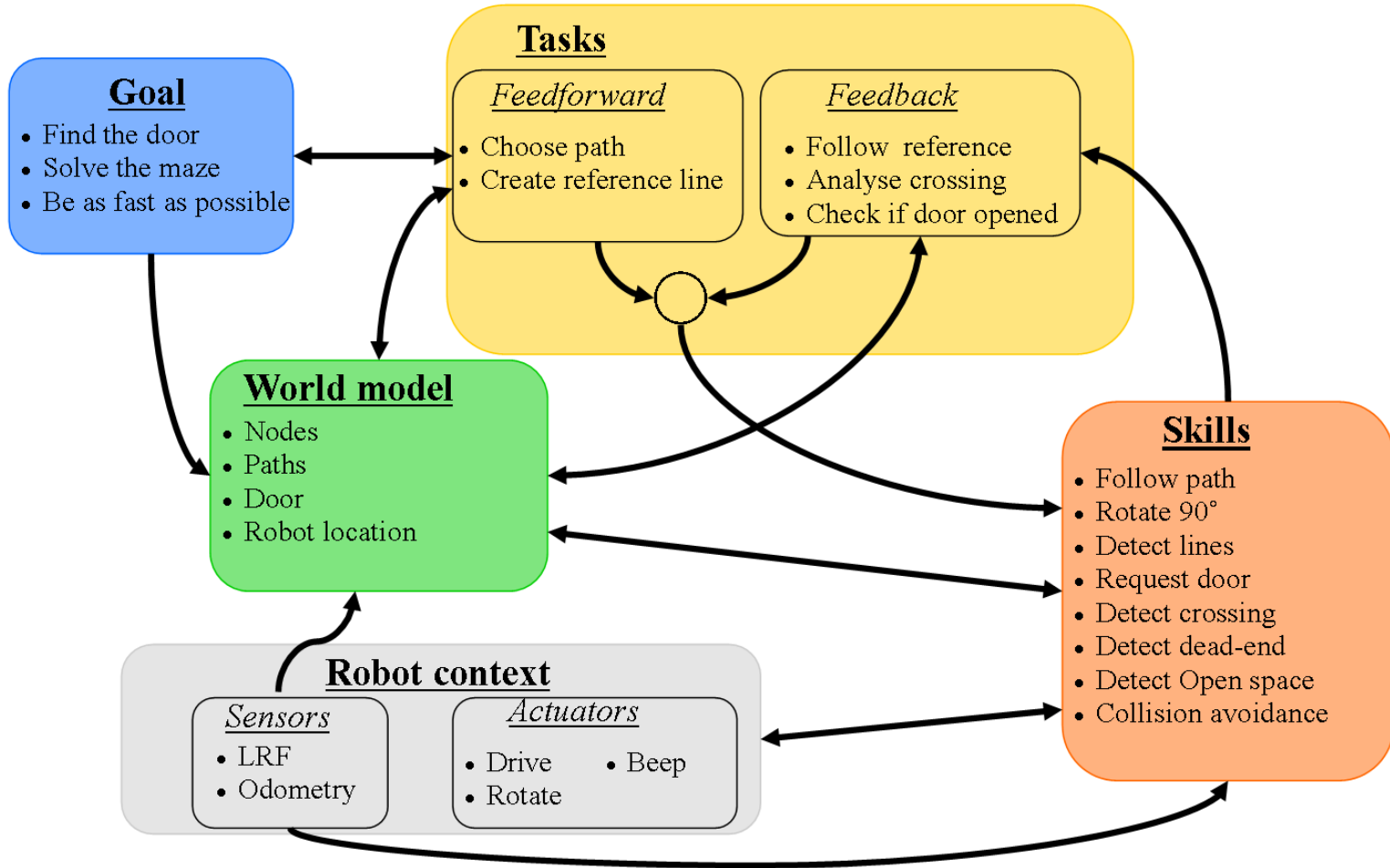
M.P. Bos

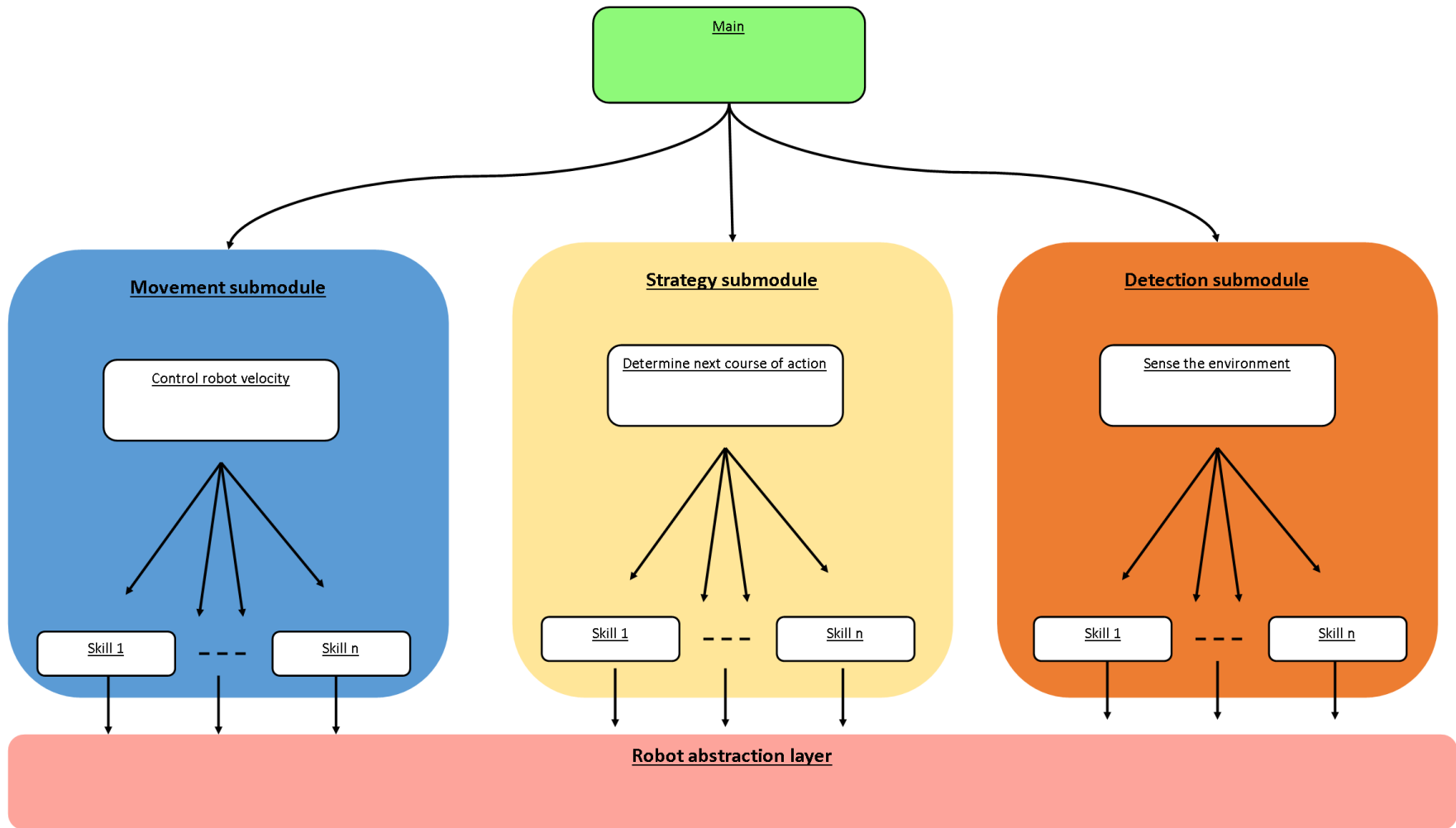
M. Cornelis

S.J.M. Koopmans

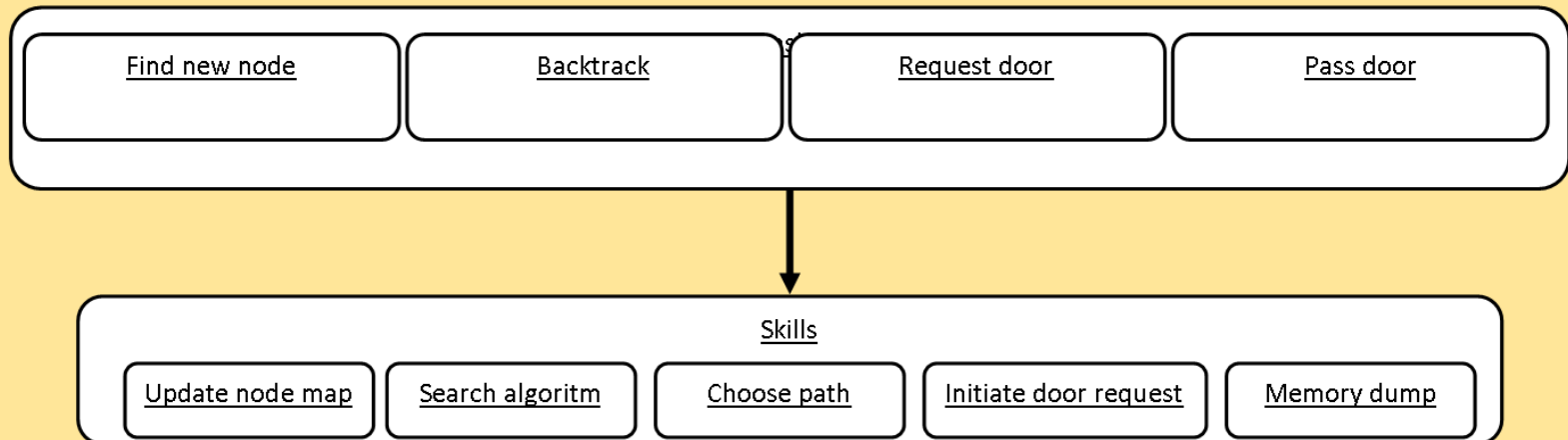
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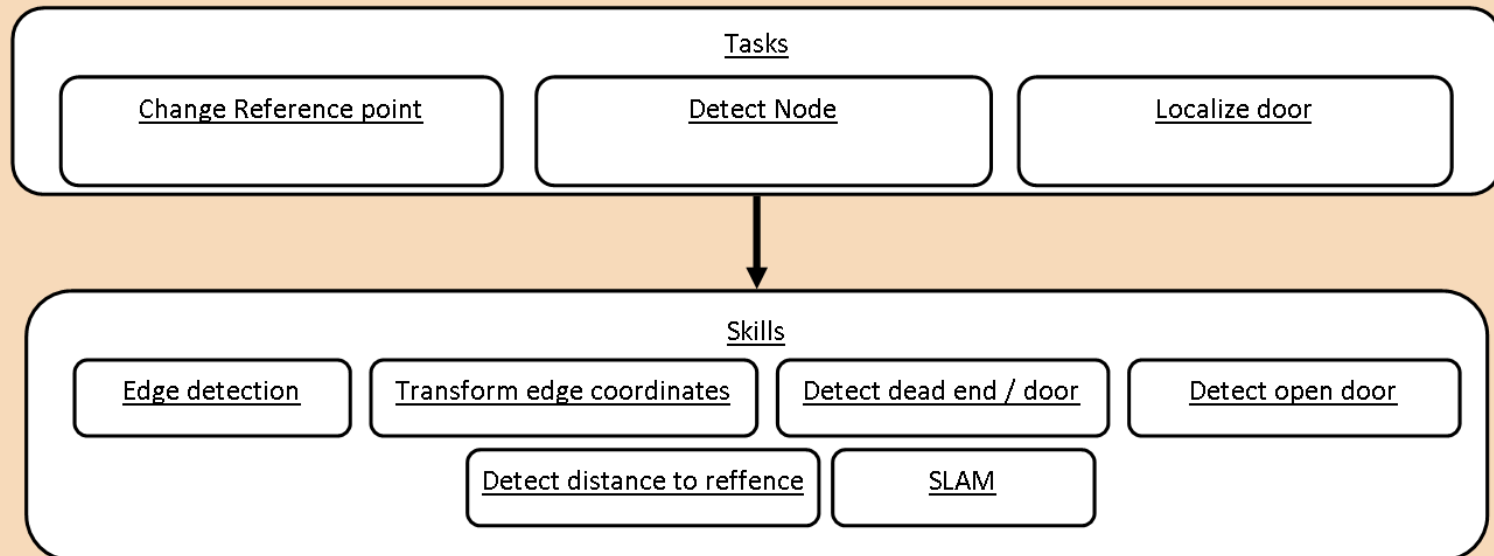




Strategy module
(Determine next course of action)



Detection module
(Sense environment)



Movement module
(Control robot velocity)

